

# Rigorous Mathematics Language with Graphs

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## 1 Introduction

This paper introduces a language in which we can make rigorous mathematical statements by constructing graphs. The language shares the title of this paper, which we shorten to GRML. The goal of GRML is to create a concrete, uniform format for making mathematical statements. Doing this allows for, among other things, the creation of computer applications which can understand, interpret, and manipulate mathematical statements directly by working on the graphs used to make said statements.

This is certainly not the first attempt to put math on computers. However, one thing which differentiates GRML from other math-computer languages is that GRML is not intended to accomplish any active tasks like proving theorems or discovering new material. GRML is a purely passive language, intended only to allow for stating the various things we mathematicians state in our work. GRML is designed to be used in other computer programs for whatever mathematical application is desired, but GRML itself does not do any processing beyond what is required to ensure a statement makes sense.

### 1.1 A Note on Computers

We can take a moment to compare two intersections between mathematics and computers which most modern mathematicians are familiar with –  $\text{\TeX}$  and ASCII/Unicode. Although  $\text{\TeX}$  is used primarily for typesetting documents, it is a full fledged computer language on its own (i.e. is Turing complete).  $\text{\TeX}$  is a language which can do things, can process things, and nobody hesitates to call it a computer language.

ASCII/Unicode, on the other hand, is merely a format for allowing computers to work with the letters and other symbols we use in written language. It is a stretch to call ASCII a computer language because it does not process information, i.e. it is not a Turing complete language. It certainly plays an important role in using computers, however. Computers are purely concrete machines: anything a computer processes must be given as a sequence of binary values, physically a sequence of voltage levels. Letters used in written language

are somewhat abstract, so they cannot be understood and processed by a computer. We use ASCII (or Unicode) to translate between letters and sequences of voltages so that we can put words into a computer.

GRML is much more like ASCII than TeX, although GRML is not so low-level as to involve actual binary data. GRML encodes abstract mathematics into graphs. There are ways to translate a graph into physical data on which a computer can work, but we are not interested in the technicalities of that step. Instead we focus on how we will take an abstract mathematical statement and state it as a graph via GRML, with the understanding that graphs are concrete enough for computers to work on directly.

## 2 The Graphs We Use

### 2.1 Terminology

In this paper we will be working with colored directed acyclic graphs. Essentially every metamathematical concept we feature in GRML will be encoded as some particular structure imposed on the classes of directed acyclic graphs with various degrees of coloring.

Our graphs consists of finitely many vertices called *members* and finitely many edges. When we say  $a \in G$  we mean that  $a$  is a member of  $G$ . By colors we mean identifiers. Coloring a particular object allows us to tell if two objects share the same color or not, we could call it labeling or naming too.

In each graph we require that each member has a color which we call the *type* of the member and another color which we call the *id* of the member. No two members of a graph can share the same id. Each edge has a color as well, we call this the *name* of the edge. Each graph itself has a color which we call the *UI* (universal identifier) of the graph and we insist that no two different graphs can share the same UI. We universally fix one color which we call *no color*. If a member is colored with no color then we say it has no type and if an edge has no color then we say it has no name. We insist that no graph can be given the UI no color.

We are not always interested in how the particular colors, such as the id of each member or the UI of each graph, are assigned. The purpose of requiring them is so that we have a tangible datum which can be used to connect information between different parts of different graphs. If we omit description of the ids of members, we implicitly assume that they have been assigned so that each member has a unique id. Likewise with UIs of graphs. Any time this information is relevant we will describe how so.

The edges are oriented so that each edge has a *parent* member and a *child* member. We denote the parent member of edge  $N$  by  $p(N)$  and the child member by  $c(N)$ . For  $a, b \in G$  if there is an edge  $N$  with  $p(N) = a$  and  $c(N) = b$  then we say  $a$  is a *parent* of  $b$  and that  $b$  is a *child* of  $a$ . We often insist that no two edges can have the same name and the same parent member in any graph. This ensures that parents can distinguish their children by name.

We introduce an order called **ancestry** inductively on  $G$  as follows: for all  $a, b \in G$ ,  $a$  is an ancestor of  $b$  if  $a$  is a parent of  $b$  or if  $a$  is a parent of an ancestor of  $b$ . If  $a$  is an ancestor of  $b$  we say  $b$  is a **descendant** of  $a$ . We insist acyclicity in that no member can be its own ancestor.

An **elder** is a member of the graph  $G$  which has no parents. Every graph has at least one elder. An **eldest** is a member  $e \in G$  such that all other members of  $G$  are descendants of  $e$ . An eldest member, if it exists, is unique.

For our applications it is often useful for a graph to have an eldest member. Any graph can be modified to contain an eldest member by inserting a member  $e$  and for each elder  $g \in G$  inserting an edge  $N_g$  with parent  $e$  and child  $g$ . If a graph has an eldest member  $e$  then we call the children of  $e$  **maximal**.

A member  $g \in G$  has **only one parent** if there is precisely one edge  $N$  whose child member is  $g$ . A graph is called a **tree** if there is an eldest member (called the **root**) and if every other member has only one parent.

One graph which we are particularly interested in consists of exactly one member and no edges. We call this the **singleton** graph. Any two singleton graphs are distinguishable by color information, particularly their UIs.

## 2.2 Graph Homomorphisms

Suppose  $G, G'$  are graphs and  $f : G \rightarrow G'$  is a function. That is,  $f$  is a function from the members of  $G$  to those of  $G'$  and from the edges of  $G$  to those of  $G'$ . We call  $f$  a **graph homomorphism** if the following hold for all members  $a, b \in G$  and all edges  $N$  in  $G$  with  $p(N) = a, c(N) = b$ :

- $p(f(N)) = f(a)$  and  $c(f(N)) = f(b)$
- $f(a)$  has the same type as  $a$
- $f(b)$  has the same type as  $b$
- $f(N)$  has the same name as  $N$

If  $G, G'$  are graphs,  $f : G \rightarrow G'$  is a graph homomorphism, and  $g \in G$ , we say  $f(g)$  is **playing the role** of  $g$  in  $G'$ .

One result which may be of interest to those developing algorithms to work with GRML graphs is this:

**Theorem 2.1.** *Let  $G$  be a graph with an eldest member  $e$ . Then there is a tree  $T$  and a graph homomorphism  $q : T \rightarrow G$  such that  $q$  takes the root of  $T$  to  $e$ .*

Making a comparison to topology, a tree can be considered a simply connected space. Then  $T$  in theorem 2.1 is an analogue of the universal cover, though the graph  $T$  is by no means unique. Fixing one such graph  $T$  essentially determines a map of  $G$ , providing a choice of path between any two vertices of  $G$  in a uniform way by looking instead at  $T$ . We won't need these details here, though, so we move on.

### 3 Typed Graphs

This section is devoted to developing enough of the language of graphs to allow for mathematical grammar. A grammatically correct statement would be  $x = y$  where  $x, y$  are integers. A grammatically incorrect statement would be  $x = y$  where  $x$  is an integer and  $y$  is a topological space, or that  $x =$  where  $x$  is an integer and we omit stating what  $x$  is supposed to be equal to. By the end of this section we will have described enough of GRML to see how grammar features.

The way to make statements as graphs is through the notion of typed graphs. We will define what a typed graph is, but the definition is recursive and we need some background structure first: we define *dictionary* then we go on to define *typed graph*. For a starting point, let  $G$  be a singleton graph with UI  $T$  and whose only member has type  $T$ . We call these **genesis** graphs and we will see that genesis graphs are typed graphs. It may be worth stating now that any typed graph  $G$  must contain an eldest member whose type is the same color as the UI of  $G$ .

A *dictionary* is a particular kind of graph. Terminology may change when referring to dictionaries, we may call the members **definitions** and the edges **dependencies**, though we retain the member/edge terminology for now. Each member of a dictionary must be typed with the same color as the UI of some typed graph. If  $G$  is a typed graph with UI  $T$  and  $D$  is a dictionary with a member of type  $T$  then we say  $D$  contains the **definition** of  $G$ . If  $D$  contains the definition of  $G$  we may just say that  $D$  contains  $G$  or that  $D$  contains  $T$ .

Part of being a typed graph includes a notion of dependency. Specifically, if  $G$  is a typed graph then there is a well-defined finite set  $\{T_i\}$  where each  $T_i$  is the UI of a typed graph upon which  $G$  depends. We say  $G$  is **independent** if this set is empty. As we will see, genesis graphs are independent.

If a dictionary  $D$  contains a member  $g$  of type  $G$ , meaning a member whose type is the same color as the UI of the typed graph  $G$ , then for each UI  $S$  upon which  $G$  depends there must be a member  $g_S \in D$  of type  $S$  and an edge  $N_S$  whose child member is  $g_S$  and whose parent member is  $g$ . We call this requirement that dictionaries must be **self-contained**. The condition that  $D$  is acyclic prevents us from making circular definitions. At this point we are not concerned with the names of the edges in a dictionary.

Suppose  $G$  is a graph,  $g$  is a non-eldest member in  $G$ , and the type of  $g$  is the UI of a typed graph  $T \neq G$ . We say  $g$  **matches its type** if there is a graph homomorphism from  $T$  to  $G$  such that  $g$  plays the role of the eldest member of  $T$ .

We are now ready to define typed graph. Suppose  $G$  is a graph. We say  $G$  is a **typed graph** if all of the following hold:

- $G$  has an eldest member  $e$
- The type of  $e$  is the UI of  $G$
- Any child of  $e$  has only one parent, namely  $e$

- Let  $X$  be all members of  $G$  which are not  $e$ . For  $x \in X$  let  $T_x$  be the type of  $x$ . For all  $x \in X$   $T_x$  is not the UI of  $G$
- For all  $x \in X$   $T_x$  is the UI of a typed graph
- For all  $x \in X$   $x$  matches its type
- There is a dictionary  $D_G$  such that for all  $x \in X$   $D_G$  contains a member of type  $T_x$

We call the set  $\{T_x : x \in X\}$  the set of types upon which  $G$  *depends*.

### 3.1 Using Typed Graphs

Typed graphs are the mechanism for making mathematical statements. What we have seen so far has given us the power to declare any object definition. An *object definition* is context required to make a mathematical statement. Object definitions are different than property definitions. Observe the standard definition of a function,

A *function*  $f : A \rightarrow B$  where  $A$  and  $B$  are sets is a relation such that for all  $a \in A$  there is a unique  $b \in B$  with  $f(a) = b$ .

Everything before the term “such that” is the object part of this definition. That is, the function  $f$  needs the sets  $A$  and  $B$  and the relation  $f$  as context before  $f$  can be said to be a function.

We say that the second half, after the “such that,” is not object definition but behavior definition. Behavior is where mathematics gets interesting, objects are just for context.

When a typed graph  $G$  encodes a statement we often refer to the members of  $G$  as *terms*. Specifically we refer to non-eldest members of  $G$  as terms. The eldest member is only used to turn our statement into a tangible GRML object, it does not in general interact with the content of the statement. The meaning of a statement is encoded in the terms, the statement itself is embodied in the eldest member.

Let’s see how to use object definitions. Suppose  $S$  is a typed graph. Then we think of  $S$  as defining an object type through the contents of the graph  $S$ . If we are then constructing another statement  $L$ , we can add a term  $s$  to  $L$  of type  $S$ . We must perform a test now to check that  $s$  is valid, namely  $s$  must match its type. We may call this that  $s$  must match its definition, seeing as we are using the type of  $s$  as its definition. If this test passes then we consider  $s$  to be an instance in  $L$  of the object type  $S$ . Type matching ensures grammatical consistency. See appendix ?? for examples of definitions given as typed graphs.

## 4 Encoding Behavior

We would like to be able to make statements which encode mathematical behavior such as making and proving claims. The typical way we add functionality

to our language is by adding more layers of coloring to the components of our graphs or by requiring some extra pieces of structure. This is commonly intended to be universal and retroactive, so we typically introduce a default value which we apply to everything covered before the new requirement was introduced.

The general process will be that each specific behavioral ability we introduce will be associated to a *statement type*. Formally the *statement type* is a color we assign to each of our typed graphs. The default value is *definition*, and a statement declared as a *definition* is interpreted as an object definition the way described in section 3.1. We think of the material presented there as passive because it only allows us to make grammatically correct statements.

If we want to describe some active behavior, we encode the action in a typed graph  $T$  and give  $T$  the statement type which corresponds to the type of action we want to perform. Then, if we are building a statement  $S$  and we want to refer to the behavior encoded in  $T$ , we construct a term  $t \in S$  of type  $T$ . We look at the statement type of  $T$  and follow whatever algorithm was described when that statement type was introduced. This algorithm may include an extra verification test, and if this test passes then the algorithm performs in  $S$  the action we originally wanted to take. The action is then successfully executed in  $S$  and if we need to refer to the execution of this action then we refer directly to the term  $t \in S$ .

The only action we are capable of at this point is defining grammatical rules and following them. This is because the only statement type we have seen so far is *definition*. We want to consider new statement types as extensions of previously understood statement types, with *definition* being the root of all of them. This gives us the ability to recover at least some of the intended meaning if we encounter an unfamiliar statement type. It also means that every statement must be grammatically correct, even if the focus is on more subtle behavior, because each statement type is a special case of *definition*.

## 4.1 Existence Claims

The first action we would like to be able to perform is that of creating new terms given others. We already have the ability to create terms in some given context, but sometimes we want to specify that a term is guaranteed to exist because of some other terms. So far we only have the ability to state what a term is, not to specify that the term comes from the context. We call this ability making or invoking a claim and we introduce the statement type *claim* for this.

Before we get to the process of constructing a claim  $T$ , we need to universally fix a genesis definition *context*. That is, we define *context* as a type and we do not require any children for this type. With this we can insert terms of type *context* in any statement graph we construct.

Now we construct the typed graph  $T$  which is supposed to make the claim that some terms exist given some other terms. First we build the contextual terms into  $T$ . These play the role of what will be required to be given when the claim is invoked and we require that there be at least one such term. We call these context terms or given terms. Once we have completed the context terms,

we add a term  $c$  of type *context* and make  $c$  the eldest term in  $T$  by inserting appropriate parent-child relationships. When we are finished  $c$  will no longer be the eldest but we need  $c$  to be an ancestor of every context term.

Now that we have the context terms covered, we insert terms into  $T$  which we would like to follow from the context. These are called our claimed terms. We insist that no claimed term can be a parent of  $c$  if we want  $T$  to be a *claim*. Claimed terms are distinguished as claimed because they are not descendants of  $c$ . Once we have inserted all the claimed terms, we cap off  $T$  with an eldest member to make  $T$  into a typed graph and we set the statement type of  $T$  to *claim*.

Formally, a *claim* is a typed graph  $T$  with statement type *claim* such that there is one and only one term  $c \in T$  of type *context*. Moreover,  $c$  must be maximal and must have at least one child. We interpret  $T$  by treating any descendant of  $c$  as context and any other term (except  $c$ ) as claimed. If we want to read  $T$  as a traditional statement with traditional quantifiers, we start with a  $\forall$  clause which contains all the descendants of  $c$ . Then for each claimed term we have a parallel statement which starts with the previous  $\forall$  clause and ends with a  $\exists$  clause corresponding to the claimed term. All terms in each clause are joined by conjunction, or “and.”

Now that we have seen how to make claims, let’s see how to invoke them. Suppose that  $T$  is a *claim* graph and that we are building the statement graph  $S$ . Suppose we have terms in  $S$  which match the context part of  $T$ . We wish to use  $T$  to construct new terms in  $S$  and to do so in a way which records that these new terms follow from the context.

Invoking the claim in  $T$  starts by inserting a term  $t$  of type  $T$  in our statement graph  $S$ . Of course, to do this, we need to already have terms in  $S$  which play the role of the given terms and the claimed terms. How we distinguish justified-by-claim terms from the rest requires some retroactive structural addition to typed graphs.

Every term in every typed graph is given another layer of coloring called *existence*. The possible values for *existence* are **given** and **justified**, with the default being *given*. We are not free to change *existence* to *justified* at will; this would defeat the purpose of proofs. Instead *justified* comes about from the following algorithm.

Before we give the algorithm we first require every typed graph  $S$  carry a graph  $P$  called the existence graph. There must be a 1-1 correspondence between members of  $P$  and members of  $S$ . If  $a, b \in P$  with  $a$  a descendant of  $b$  in  $P$ , it must be that  $b$  is *justified* in  $S$  and we interpret the relationship as that the justification of  $b$  relies on  $a$ .

No statement can have a term with an *existence* of *justified* without some corresponding reliance in  $P$ . If we add a feature to GRML which results in a graph being considered valid with a *justified* term which has no other terms on which it relies, then we will have broken GRML. There are no absolute truths in GRML – all truth is relative.

Suppose  $a, b \in P$  and  $a$  is a child of  $b$ . The name of this parent-child edge must be the id of a term  $t \in S$  where  $t$  is a term of statement type *claim*. That

is, the graph  $T$  which defines the type of  $t$  must have statement type *claim* (or some extension of *claim*). In this way the existence graph records which terms are justified, which claims were used, which terms invoked these claims, and in each invocation which terms were given as context. The requirement that  $P$  be acyclic ensures that no term can justify itself.

Now that we have the necessary structure of existence graphs, we can describe the algorithm for invoking a *claim*. Suppose  $T$  is a *claim*,  $S$  is a statement, and we have already constructed the terms in  $S$  which we want to use as context in the claim we are invoking. The next thing we do is insert terms to  $S$  which we want to be justified by this invocation. Then we add  $t$  and set its children appropriately.

At this point we first check that  $t$  matches its type  $T$  as a *definition*. Once this is verified, we need to account for the actual claim by manipulating the proof graph. Suppose  $C$  is the set of terms in  $S$  which play the roles of context terms in  $T$  and let  $E$  be the terms in  $S$  which play the roles of claimed terms. For every  $c \in C$  and  $e \in E$ , we make  $e$  a parent of  $c$  in  $P$  with the child name  $t$ .

If doing this introduces a cycle in  $P$  then we stop and the test failed. If  $P$  remains acyclic then the test passed and we have successfully invoked the claim. We now set the *existence* of every term in  $E$  to be *justified*.

## 4.2 Testables

Another useful behavior we want to have available is boolean truth. Suppose we have a definition  $D$  and a term  $d$  of type  $D$ . If we are considering  $D$  as just a definition, we cannot refer to  $d$  as being true or false. The only thing we can say about  $d$  is what its children are, i.e. in what context  $d$  resides. With the addition of *claim*, we can also say whether  $d$  is given or justified, but not whether  $d$  is true or false. It is very common in math, however, to use the dichotomy of true and false. In fact, we could consider the fundamental purpose of proof as striving to show that something must be true. We introduce this behavior of allowing us to consider at all whether  $d$  is true or false through the statement type *testable*.

We do not want to blindly make every concept testable. That adds unnecessary complication and does not even make sense with the rest of the language. If we define Set with a genesis graph, a natural approach which we see in practice in the appendix, that means sets need no context to exist. Essentially, that means the phrase “Let  $X$  be a set” makes sense on its own. We could also read that as “ $X$  is a set” where this is the introduction of  $X$  and is the first thing we state. If Set were testable, that would mean the phrase “ $X$  is a set” could be either true or false. Truth is not really a problem because that is in some sense what we meant anyway, but what does it mean for this statement to be false? The only thing we know about  $X$  is that  $X$  is a set, and if that statement is false then what is  $X$ ?

We avoid this confusion by not making the genesis definition Set testable. If Set is just a definition, it does not make sense to ask about the validity of the phrase “ $X$  is a set.” That phrase is neither true nor false, we interpret it

as only existing in its context. Being a genesis graph there is no context, so we interpret “ $X$  is a set” as merely being a statement and we prefer to phrase it “Let  $X$  be a set” to avoid the temptation of thinking it can be tested. In general we do not want genesis graphs to be *testable* because falsehood does not make sense without context.

An example of something we do want to be testable is the concept of emptiness of a set: if  $X$  is a set then  $X$  is empty or not. We can imagine performing a test to decide if  $X$  is empty or not if we are given the set  $X$ . In this case the test is to try to find an element of  $X$ . We want to be assured that, in principle, this test will always give a result. Moreover we want this test to be exclusive and well-defined in that  $X$  should be either empty or not, and not be both, regardless of how we approach finding out. This behavior is precisely what we mean by *testable* and when we declare set emptiness to be testable we are assuming this behavior.

The only requirement a typed graph must pass before being able to be marked as *testable* is that it is not a genesis graph. There is no requirement for a term of type *testable* in addition to *definition*, the only requirement is that terms match their definitions.

### 4.3 Implications

Note that existence claims have no knowledge of testability. This means, in particular, that we cannot negate an existence claim. This is a serious hole which we fill now with a new statement type, the *implication*. The statement type of *implication* extends that of *claim*.

An implication has three components: context, assumed, and claimed. If we want to look at an *implication* as a *claim*, we consider the context (rel. implication) and assumed portions together as the context (rel. claim) component. The claimed component plays the same role in both interpretations. What makes an implication different from a claim is that every term in the assumed and claimed sections must be of type *testable*.

Formally we universally fix a genesis graph *assumption*. An *implication* is a typed graph  $S$  with precisely one term  $c$  of type *context* and one term  $a$  of type *assumption*. We require  $c$  to be a child of  $a$  and  $a$  to be maximal. Any descendant of  $c$  is called a context term, any descendant of  $a$  which is not a context term is called an assumed term, and any other term is called a claimed term.

The distinction between context and assumed is more than just that assumed terms must be testable. We may choose to put some testable terms in the context portion even though they could be placed in the assumed portion. The distinction allows us fine control over things like taking the contrapositive or converse of an implication. We can only consider assuming, validating, or negating terms in the assumed or claimed sections – we do not consider context terms as testable so we do not mention them as true or false. They are merely context.

Before describing how invoking an implication works we need to describe proof graphs. Every statement  $S$  must carry a graph  $P$  called the proof graph. The idea is similar to the existence graph, but now we consider only *testable* terms.

Every member  $p$  of  $P$  corresponds to a *testable* term in  $S$ . We insist  $p$  be designated (colored) as *true* or *false*, we call this the truth value of  $p$ . Any time  $p, q \in P$  with  $p$  a parent of  $q$ , the child name must be the id of a corresponding term in  $S$  of type *implication*.

### 4.3.1 Contradiction

One of the most powerful tools available to a mathematician is contradiction. Without it we would be unable to prove any but the simplest claims. In fact, in some sense, in GRML we are going to interpret proof as the pursuit of contradiction in the effort to avoid it. That is, contradiction will be fundamental to proof as we implement it so we now discuss contradiction in GRML.

We universally fix a genesis graph called *contradiction*. This defines the type *contradiction*, so according to our rules we can arbitrarily insert terms of type *contradiction* into our statements. However, recall we default terms to the existence level of *given*, which we can also treat as assumed. While we are free in mathematics to assume a contradiction at any point, doing so typically destroys any meaning we are trying to convey. We are only interested in when we can prove a contradiction in some context, meaning when a term of type *contradiction* is *justified*. Moreover we attempt to avoid this situation, so we typically describe how a *justified contradiction* can come about specifically so that we do not wind up in that situation.

As a rule, we limit our statements to have at most one term of type *contradiction*, and we do not want such a term unless it is *justified* or about to be *justified*. This is more of a style rule than a fundamental requirement but it helps keep things organized.

We want to interpret contradiction as being equivalent to simultaneous truth and falsehood. To do this, we introduce a rule for when contradictions can be *justified*. Suppose  $S$  is the statement we are currently constructing and  $T$  is some testable type. If we have two terms  $t, f \in S$ , both of type  $T$ , and both with exactly the same children, but  $t$  is true and  $f$  is false, then we *justify* a contradiction term  $c$ . In the existence graph  $c$  is made to be a parent of both  $t$  and  $f$ , with corresponding child names *true* and *false*. If a statement graph  $S$  has a *justified* member of type *contradiction* then  $S$  is said to be a contradiction or  $S$  is said to be in contradiction.